

GVI in Function Spaces

Gaussian Measures meet Bayesian Deep Learning

Veit D. Wild* , Robert Hu* and Dino Sejdinovic

Department of Statistics

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Outline

1. Background
 - Bayesian Deep Learning
 - Variational Inference in Function Spaces
 - Generalised Variational Inference
 - Gaussian Measures on Hilbert Spaces
2. Gaussian Wasserstein Inference
 - Model description
 - Parameterisation of GWI
3. Experiments



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Bayesian Deep Learning



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- Bayesian Neural Network:
Sample $W \sim p(w)$ and obtain random function $F(x; W)$ as prior.
- Predictions for arbitrary $x^* \in \mathcal{X}$ follow from Bayes rule:

$$p(y^* | \mathcal{D}) = \int p(y^* | w) p(w | \mathcal{D}) dw \quad (2)$$

$$= \int p(y^* | f(x^*; w)) p(w | \mathcal{D}) dw \quad (3)$$



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Let $q(\mathbf{w}) = q(\mathbf{w}; \nu)$ be a distribution with unknown parameters ν . Learn ν by maximising

$$\mathcal{L}(\nu) := \mathbb{E}_{q(\mathbf{w})} [\log p(y|\mathbf{w})] - \mathbb{D}_{\text{KL}}(q(\mathbf{w}), p(\mathbf{w})), \quad (5)$$

which is (often) tractable. Use $q(\mathbf{w}; \nu) \approx p(\mathbf{w}|\mathcal{D})$.



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- What priors on the function space are induced by $p(w)$?



Variational Inference in Function Spaces



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- How to specify priors on infinite dimensional function spaces?
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- The KL-divergence is (in general) intractable in infinite dimensions and may even be infinite [Burt et al., 2020].
→ use generalised variational inference in infinite dimensions!



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$$q^*(w) := \operatorname{argmin}_{q \in \mathcal{Q}} \left\{ \mathbb{E}_{q(w)} \left[\sum_{n=1}^N \ell(y_n, w) \right] + D(q(w), p(w)) \right\}, \quad (7)$$



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$$\mathcal{L} := -\mathbb{E}_{\mathbb{Q}}[\log p(y|F)] + \mathbb{D}(\mathbb{Q}^F, \mathbb{P}^F), \quad (8)$$

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- How to define priors and variational measures \mathbb{P}^F and \mathbb{Q}^F in infinite dimensions?



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Definition (Gaussian Random Element)

A random mapping $F : \Omega \rightarrow H$ is called Gaussian random element (GRE) if and only if

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and the (linear) covariance operator $C : H \rightarrow H$ of F is defined as

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Definition (Gaussian Measure)

Let $F \sim \mathcal{N}(m, C)$ be a GRE. Then P defined as

$$P(A) := \mathbb{P}^F(A) := \mathbb{P}(F \in A) \quad (13)$$

for any (measurable) $A \subset H$ is called a Gaussian measure.



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with:

$$C_P g := \int k(\cdot, x') g(x') d\rho(x'), \quad C_Q g := \int r(\cdot, x') g(x') d\rho(x') \quad (15)$$

for all $g \in L^2(\mathcal{X}, \rho, \mathbb{R})$ where k and r are trace-class kernels.



Regression



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For regression:

$$p(\mathbf{y}|\mathbf{F}) := \prod_{n=1}^N p(y_n|\mathbf{F}) := \prod_{n=1}^N \mathcal{N}(y_n | \mathbf{F}(\mathbf{x}_n), \sigma^2), \quad (16)$$

where $\sigma^2 > 0$.



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where $\sigma^2 > 0$.

The Wasserstein distance is tractable [Gelbrich, 1990]:

$$W_2^2(P, Q) = \|m_P - m_Q\|_2^2 + \text{tr}(C_P) + \text{tr}(C_Q) - 2 \cdot \text{tr} \left[(C_P^{1/2} C_Q C_P^{1/2})^{1/2} \right], \quad (17)$$

where $\text{tr}(\cdot)$ denotes the trace of an operator and $C_P^{1/2}$ is the square root of the positive, self-adjoint operator C_P .



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Further:

$$\text{tr}(C_P) = \int k(x, x) d\rho(x) \approx \frac{1}{N} \sum_{n=1}^N k(x_n, x_n) \quad (20)$$

$$\text{tr}(C_Q) = \int r(x, x) d\rho(x) \approx \frac{1}{N} \sum_{n=1}^N r(x_n, x_n) \quad (21)$$



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The last term can be approximated as

$$\text{tr} \left[(C_P^{1/2} C_Q C_P^{1/2})^{1/2} \right] \approx \frac{1}{\sqrt{NN_S}} \sum_{s=1}^{N_S} \sqrt{\lambda_s(r(X_S, X)k(X, X_S))}, \quad (22)$$



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where $X_S := (x_{S,1}, \dots, x_{S,N_S})$, $N_S \in \mathbb{N}$ with:

$$X_{S,1}, \dots, X_{S,N_S} \stackrel{\text{ind.}}{\sim} \hat{\rho} \quad (23)$$

$$r(X_S, X) := (r(x_{S,s}, x_n))_{s,n} \quad (24)$$

$$k(X, X_S) := (k(x_n, x_{S,s}))_{n,s} \quad (25)$$

and $\lambda_s(r(X_S, X)k(X, X_S))$ denotes the s -th eigenvalue of the matrix $r(X_S, X)k(X, X_S) \in \mathbb{R}^{N_S \times N_S}$.



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→ very scalable for typical $N_S, N_B \ll N$, e.g. $N_S = N_B = 100$



Recovering Other Methods



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- Stochastic Variational Gaussian processes (SVGP) [Titsias, 2009]:

$$m_Q(\mathbf{x}) := m_P(\mathbf{x}) + \sum_{m=1}^M \beta_m k_m(\mathbf{x}) \quad (30)$$

$$r(\mathbf{x}, \mathbf{x}') := k(\mathbf{x}, \mathbf{x}') - \mathbf{k}_Z(\mathbf{x})^T \mathbf{k}(Z, Z)^{-1} \mathbf{k}_Z(\mathbf{x}) + \mathbf{k}_Z(\mathbf{x})^T \Sigma \mathbf{k}_Z(\mathbf{x}), \quad (31)$$

where $\beta = (\beta_1, \dots, \beta_M) \in \mathbb{R}^M$ and $\Sigma \in \mathbb{R}^{M \times M}$ are variational parameters. Further $Z = (Z_1, \dots, Z_M)$ with $\{Z_m\}_{m=1}^M \stackrel{\text{iid}}{\sim} \hat{\rho}$.



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- Decoupled SVGPs [Cheng and Boots, 2017]: Same kernel r as in SVGP but mean

$$m_Q(x) := m_P(x) + \sum_{n=1}^{\tilde{N}} \beta_n k_n(x), \quad (32)$$

where $\tilde{N} > M$.



GWI-net



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GWI-net

Use neural net for posterior mean



GWI-net

Use neural net for posterior mean

- Let $L \in \mathbb{N}$ be the number of hidden layers.
- Let $D_\ell, \ell = 0, \dots, L + 1$ be the width of layer ℓ with $D_0 := D$.
- Define $g^1(\mathbf{x}) := W^1\mathbf{x} + \mathbf{b}^1$ and further

$$\mathbf{h}^\ell(\mathbf{x}) := \phi(\mathbf{g}^\ell(\mathbf{x})), \quad (33)$$

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and the SVGP kernel r in (31) for the posterior covariance.



Contents

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 - Bayesian Deep Learning
 - Variational Inference in Function Spaces
 - Generalised Variational Inference
 - Gaussian Measures on Hilbert Spaces
2. Gaussian Wasserstein Inference
 - Model description
 - Parameterisation of GWI
3. Experiments



Toy Examples: GWI-net on 1-D data

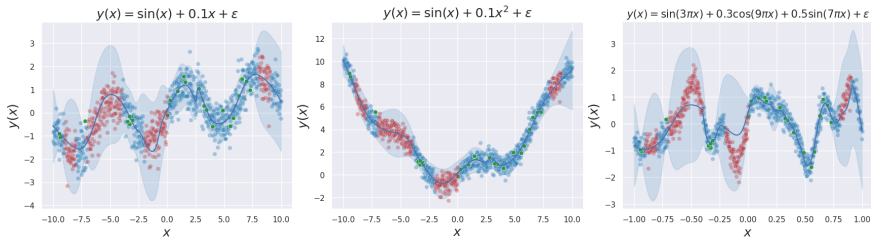


Figure 1: ■ : Training data ■ : Unseen data ■ : Inducing points
We use $N = 1000$ equidistant points and add white noise with $\epsilon \sim \mathcal{N}(0, 0.5^2)$.
The plot shows $m_Q(x) \pm 1.96\sqrt{\mathbb{V}[Y^*(x)|Y]}$ where $\mathbb{V}[Y^*(x)|Y]$ is the posterior predictive variance given as $r(x, x) + \sigma^2$.



Toy Examples: GWI-net and “in-between” uncertainty

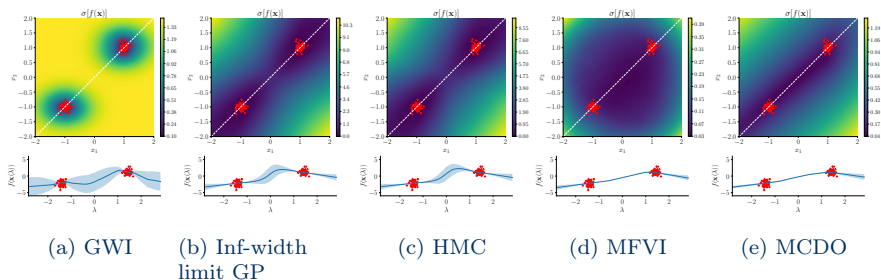


Figure 2: Regression on a 2D synthetic dataset (red crosses). The colour plots show the standard deviation of the output, $\sigma[f(\mathbf{x})]$, in 2D input space. The plots beneath show the mean with 2-standard deviation bars along the dashed white line (parameterised by λ). MFVI and MCDO are overconfident for $\lambda \in [-1, 1]$.



UCI Regression



UCI Regression

Dataset	N	D	GWI								$\alpha = 0.5$	FBNN	EXACT GP
			SVGP	DNN-SVGP	FVI	VIP-BNN	VIP-NP	BBB	VDO				
BOSTON	506	13	2.8±0.31	2.27±0.06	2.33±0.04	2.45±0.04	2.45±0.03	2.76±0.04	2.63±0.10	2.45±0.02	2.30±0.10	2.46±0.04	
CONCRETE	1030	8	3.24±0.09	2.64±0.06	2.88±0.06	3.02±0.02	3.13±0.02	3.28±0.01	3.23±0.01	3.06±0.03	3.09±0.01	3.05±0.02	
ENERGY	768	8	1.81±0.19	0.91±0.12	0.58±0.05	0.56±0.04	0.60±0.03	2.17±0.02	1.13±0.02	0.95±0.09	0.68±0.02	0.54±0.02	
KIN8NM	8192	8	-0.86±0.38	-1.2±0.03	-1.15±0.01	-1.12±0.01	-1.05±0.00	-0.81±0.01	-0.83±0.01	-0.92±0.02	N/A±0.00	N/A±0.00	
POWER	9568	4	3.35±0.22	2.74±0.02	2.69±0.00	2.92±0.00	2.90±0.00	2.83±0.01	2.88±0.00	2.81±0.00	N/A±0.00	N/A±0.00	
PROTEIN	45730	9	2.84±0.04	2.87±0.0	2.85±0.00	2.87±0.00	2.96±0.02	3.00±0.00	2.99±0.00	2.90±0.00	N/A±0.00	N/A±0.00	
RED WINE	1588	11	0.97±0.02	0.76±0.08	0.97±0.06	0.97±0.02	1.20±0.04	1.01±0.02	0.97±0.02	1.01±0.02	1.04±0.01	0.26±0.03	
YACHT	308	6	2.37±0.55	0.29±0.1	0.59±0.11	-0.02±0.07	0.59±0.13	1.11±0.04	1.22±0.18	0.79±0.11	1.03±0.03	0.10±0.05	
NAVAL	11934	16	-7.25±0.08	-6.76±0.1	-7.21±0.06	-5.62±0.04	-4.11±0.00	-2.80±0.00	-2.80±0.00	-2.97±0.14	-7.13±0.02	N/A±0.00	
Mean Rank			5.5	2.06	2.22	3.33	4.94	7	6.11	4.83			

Table 1: The table shows the average test NLL on several UCI regression datasets. We train on random 90% of the data and predict on 10%. This is repeated 10 times and we report mean and standard deviation. The results for our competitors are taken from Ma and Hernández-Lobato [2021].



Classification



Classification

Model	FMNIST			CIFAR 10		
	Accuracy	NLL	OOD-AUC	Accuracy	NLL	OOD-AUC
GWI-net	93.25 ±0.09	0.250 ±0.00	0.959 ±0.01	83.82 ±0.00	0.553 ±0.00	0.618 ±0.00
FVI	91.60±0.14	0.254±0.05	0.956±0.06	77.69 ±0.64	0.675±0.03	0.883±0.04
MFVI	91.20±0.10	0.343±0.01	0.782±0.02	76.40±0.52	1.372±0.02	0.589±0.01
MAP	91.39±0.11	0.258±0.00	0.864±0.00	77.41±0.06	0.690±0.00	0.809±0.01
KFAC-LAPLACE	84.42±0.12	0.942±0.01	0.945±0.00	72.49±0.20	1.274±0.01	0.548±0.01
RITTER et al.	91.20±0.07	0.265±0.00	0.947±0.00	77.38±0.06	0.661±0.00	0.796±0.00

Table 2: We report average accuracy, NLL and OOD-AUC on test data for 10 different train/test splits.



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